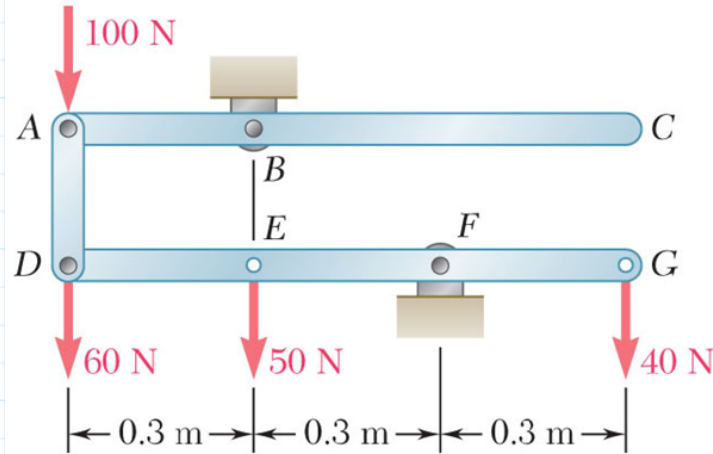


P10.1

- $l := .3 \cdot m$  Distância entre os nós do mecanismo
- $F_A := 100 \text{ N}$  Forças nos nós
- $F_D := 60 \text{ N}$
- $F_E := 50 \text{ N}$
- $F_G := 40 \text{ N}$



$$y_C = 2 \cdot l \cdot \sin(\theta) \quad y_A = -l \cdot \sin(\theta) \quad y_D = y_A$$

$$\delta y_C = 2 \cdot l \cdot \cos(\theta) \cdot \delta\theta \quad \delta y_A = -l \cdot \cos(\theta) \cdot \delta\theta \quad y_D = -l \cdot \sin(\theta)$$

$$\delta y_D = -l \cdot \cos(\theta) \cdot \delta\theta$$

$$y_E = \frac{y_D}{2} \quad y_G = -y_E$$

$$y_E = -\frac{l}{2} \cdot \sin(\theta) \quad y_G = \frac{l}{2} \cdot \sin(\theta)$$

$$\delta y_E = -\frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta \quad \delta y_G = \frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta$$

$$\sum U = 0$$

substitute,  $\delta y_C = 2 \cdot l \cdot \cos(\theta) \cdot \delta\theta$

substitute,  $\delta y_A = -l \cdot \cos(\theta) \cdot \delta\theta$

substitute,  $\delta y_D = -l \cdot \cos(\theta) \cdot \delta\theta$

substitute,  $\delta y_E = -\frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta$

substitute,  $\delta y_G = \frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta$

factor,  $l \cdot \delta\theta \cdot \cos(\theta)$

explicit

$$F_C \cdot \delta y_C = -F_A \cdot \delta y_A - F_D \cdot \delta y_D - F_E \cdot \delta y_E - F_G \cdot \delta y_G \rightarrow 2 \cdot l \cdot \delta\theta \cdot F_C \cdot \cos(\theta) = l \cdot \delta\theta \cdot F_A \cdot \cos(\theta) + \frac{l \cdot \delta\theta \cdot F_E \cdot \cos(\theta)}{2} - \frac{l \cdot \delta\theta \cdot F_G \cdot \cos(\theta)}{2} +$$

$$\theta := 0 \text{ deg}$$

$$F_C := 2 \cdot F_C = F_A + \frac{F_E}{2} - \frac{F_G}{2} + F_D \xrightarrow{\text{explicit}} \frac{F_A}{2} + \frac{F_D}{2} + \frac{F_E}{4} - \frac{F_G}{4} = 82.5 \text{ N}$$

*solve, F<sub>C</sub>*

10.3

$$\text{substitute, } \delta y_A = -l \cdot \cos(\theta) \cdot \delta\theta$$

$$\text{substitute, } \delta y_D = -l \cdot \cos(\theta) \cdot \delta\theta$$

$$\text{substitute, } \delta y_E = -\frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta$$

$$\text{substitute, } \delta y_G = \frac{l}{2} \cdot \cos(\theta) \cdot \delta\theta$$

$$M_{ABC} \cdot \delta\theta = -F_A \cdot \delta y_A - F_D \cdot \delta y_D - F_E \cdot \delta y_E - F_G \cdot \delta y_G \xrightarrow{\text{explicit}} \delta\theta \cdot M_{ABC} = \frac{l \cdot \cos(\theta) \cdot (2 \cdot \delta\theta \cdot F_A + \delta\theta \cdot F_E - \delta\theta \cdot F_G + 2 \cdot \delta\theta \cdot F_D)}{2}$$

$$\theta := 0$$

$$M_{ABC} := \frac{l \cdot \cos(\theta) \cdot (2 \cdot F_A + F_E - F_G + 2 \cdot F_D)}{2} = 49.5 \text{ N} \cdot \text{m}$$